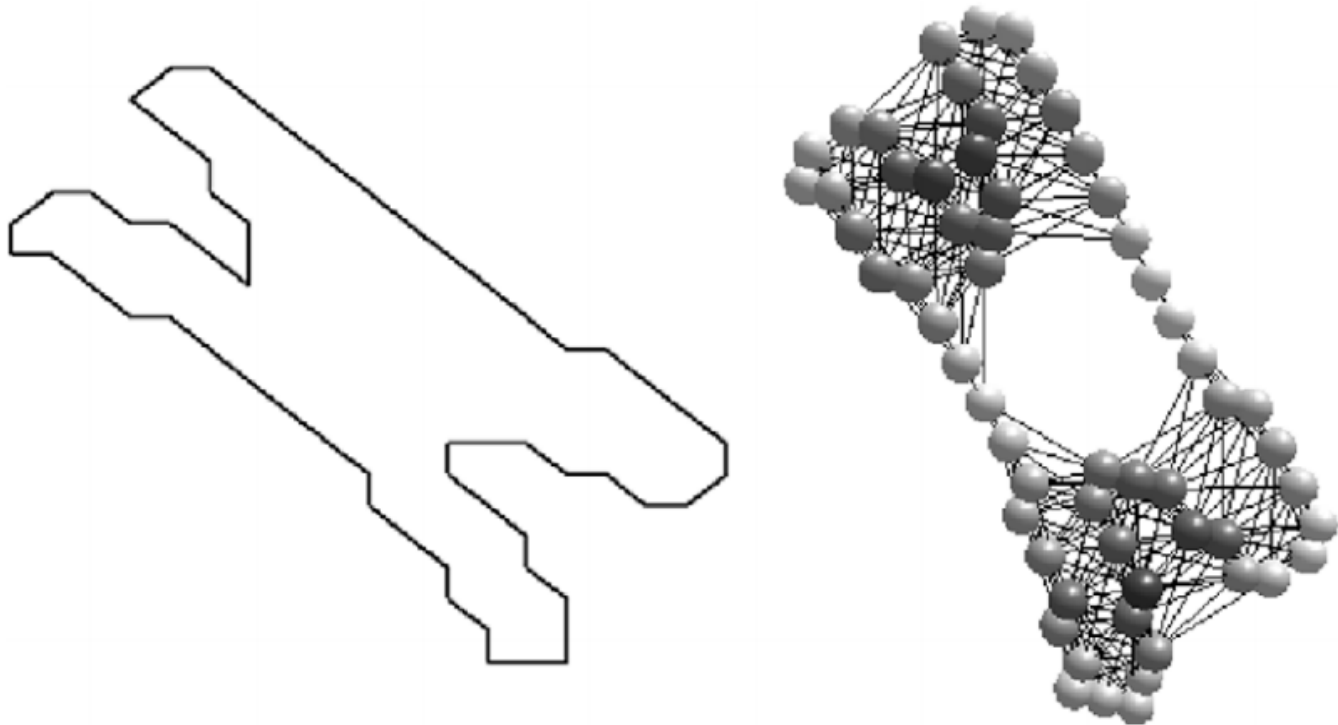


Complex networks in computer vision

Pavel Voronin

Shape to Network



[Backes 2009], [Backes 2010a], [Backes 2010b]

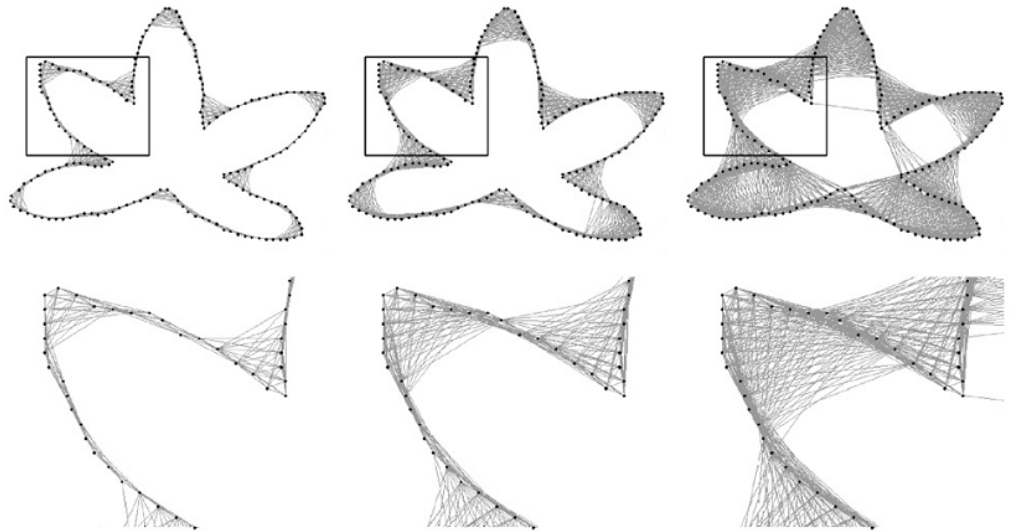
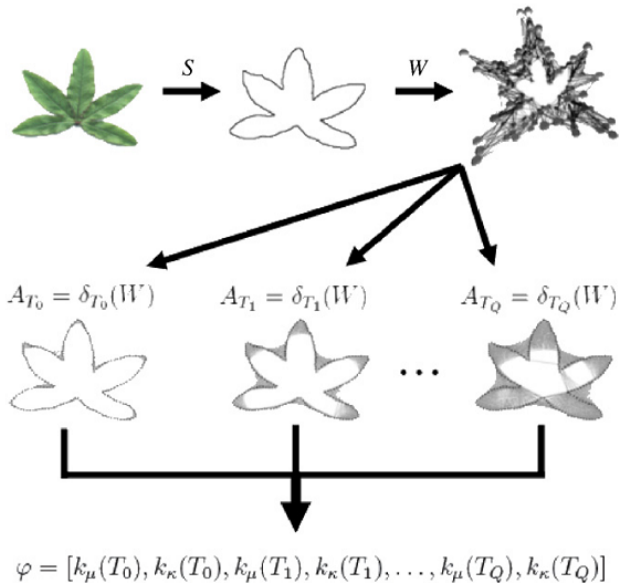
Weights + thresholds

$$d(s_i, s_j) = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}.$$

$$w_{ij} = W([w_i, w_j]) = d(s_i, s_j),$$

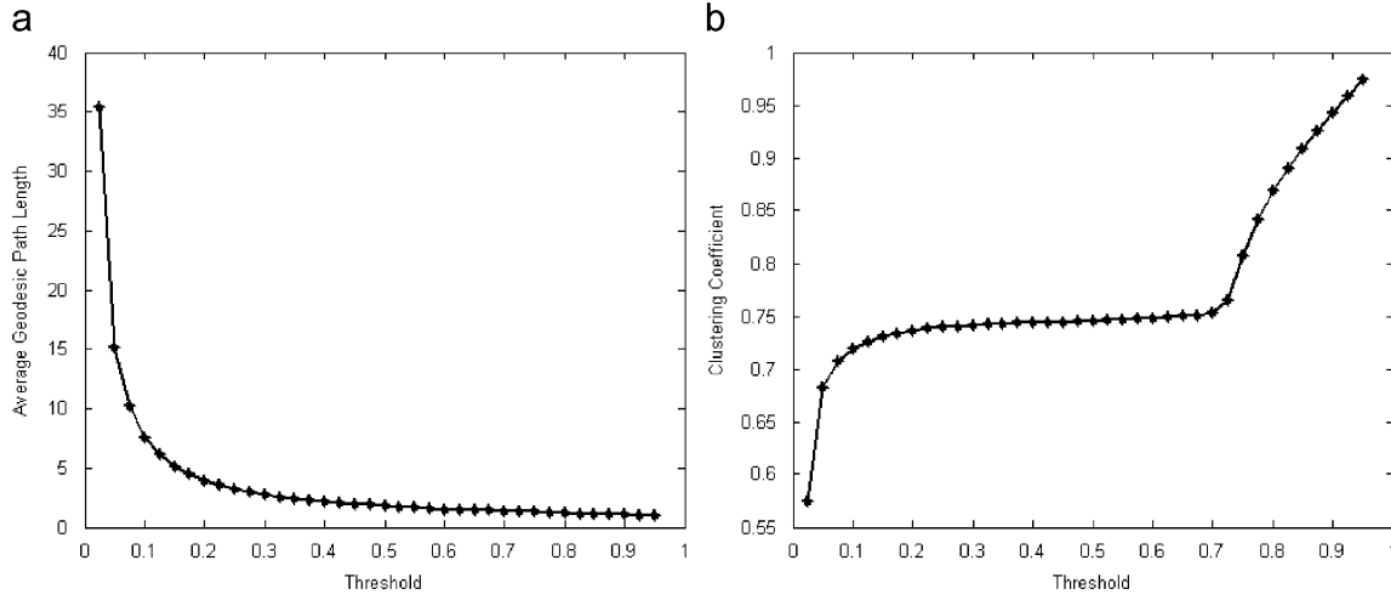
$$W = \frac{W}{\max_{w_{ij} \in W}}.$$

$$A_{T_l} = \delta_{T_l}(W) = \forall w \in W \begin{cases} a_{ij} = 0 & \text{if } w_{ij} \geq T_l, \\ a_{ij} = 1 & \text{if } w_{ij} < T_l. \end{cases}$$



Feature vectors

Features = characteristics of thresholded undirected binary networks: degree or joint degree (avg / min / max), avg path length, clustering coefficient, etc.



Multiscale Fractal Dimension

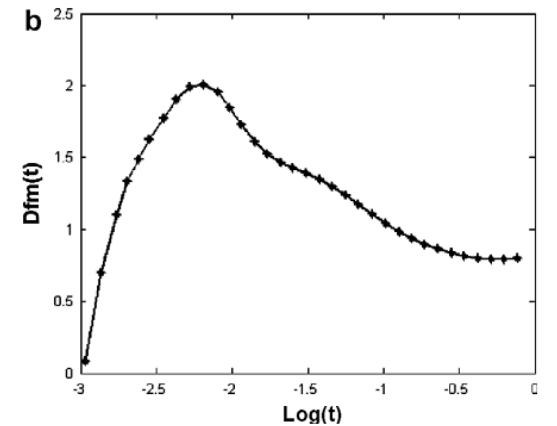
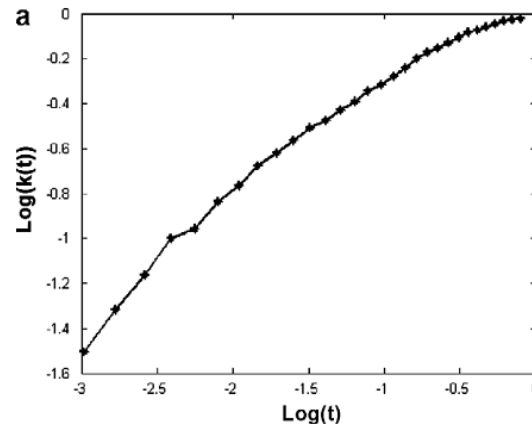
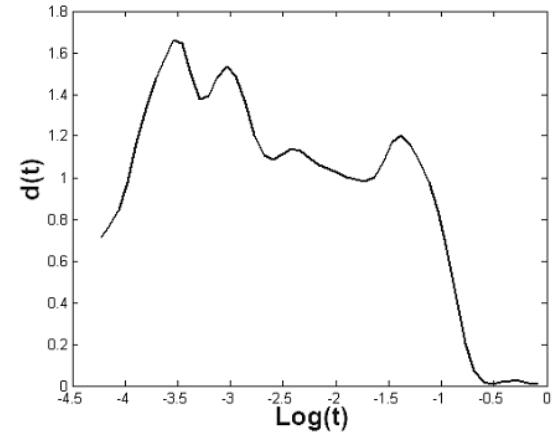
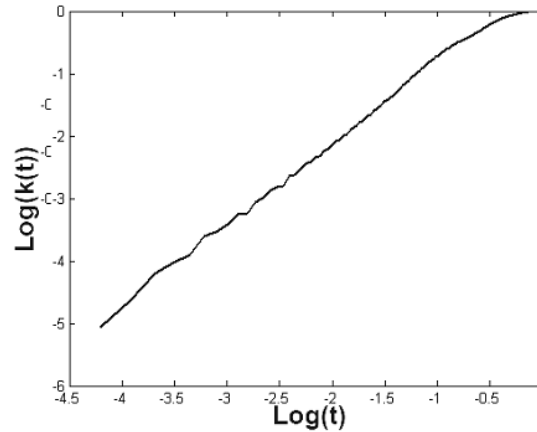
$$k \approx l^d$$

fractal dimension

$$d = \lim_{t \rightarrow 0} \frac{\log k(t)}{\log t}$$

Multi-Scale Fractal Dimension

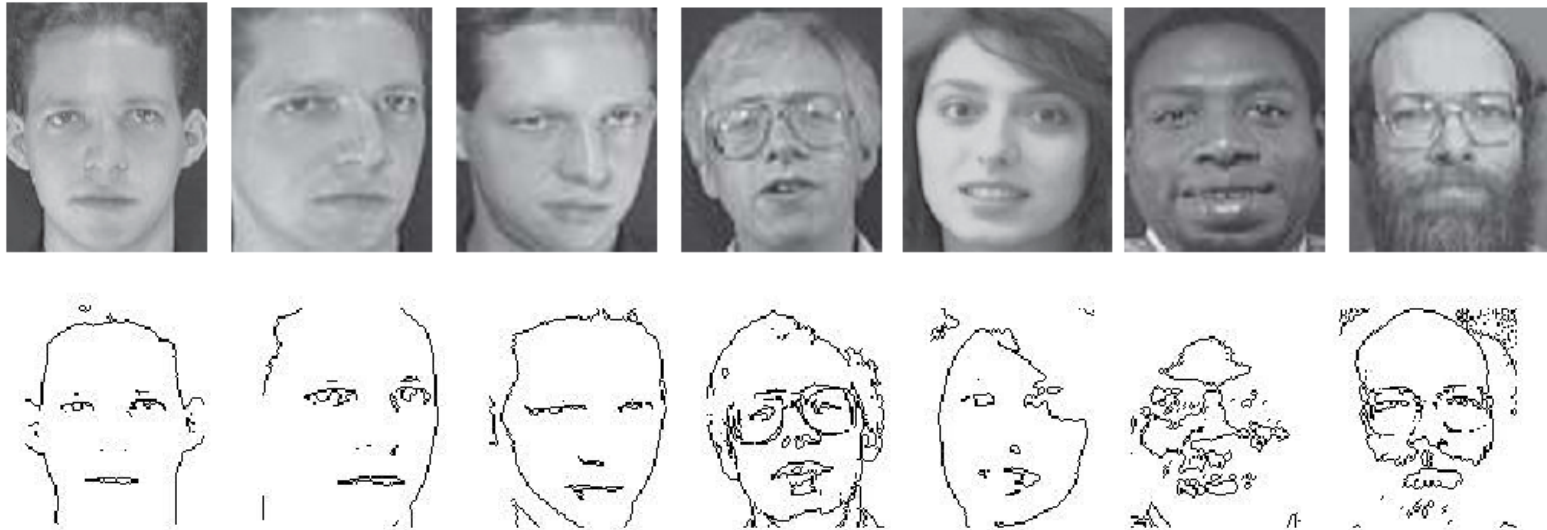
$$d(t) = \frac{d \log k(t)}{d \log t}$$



Properties

- Only uses distances
 - => rotation invariant
- Weights normalized by max distance
 - => scale invariant
- Uses pixels not curve elements
 - => robust to noise and outliers
 - => applicable to skeletons, multiple contours

Face recognition



[Goncalves 2010], [Tang 2012a]

Multiple binarization thresholds



Figure 4. Image contours of black people with different values of t^i

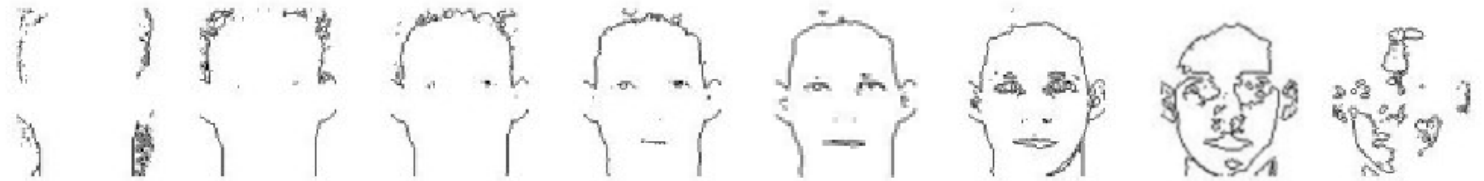


Figure 5. Image contours of white people with different values of t^i

Texture to Network

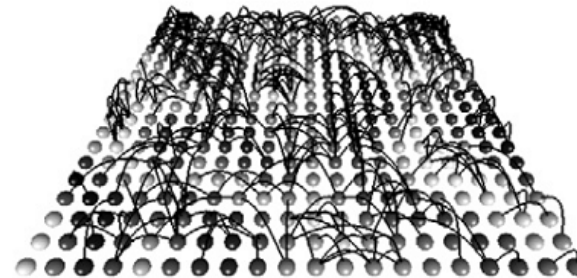
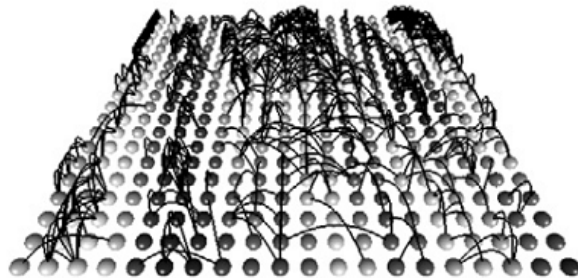
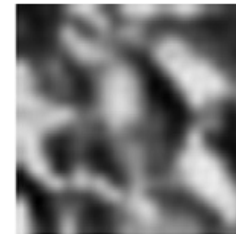
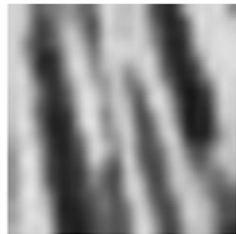
$$E = \left\{ e = (v_{x,y}, v_{x',y'}) \in I \times I \mid \sqrt{(x - y')^2 + (x' - y)^2} \leq r \right\}.$$

$$w(e) = (x - x')^2 + (y - y')^2 + r^2 \frac{|I(x,y) - I(x',y')|}{L}$$

44	31	31	29	35	103	39	29	31
25	23	27	21	42	91	56	20	32
28	18	21	37	69	56	49	21	34
82	20	52	140	70	40	44	30	33
113	17	45	155	52	44	50	35	31
95	20	12	20	58	129	26	32	36
72	28	28	14	60	52	39	34	35
38	15	13	17	53	62	40	27	37
18	16	14	10	38	65	39	26	35

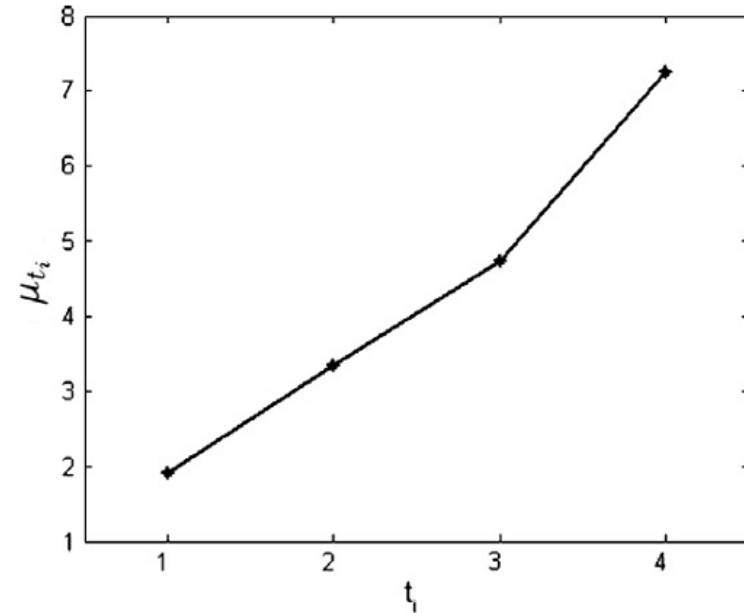
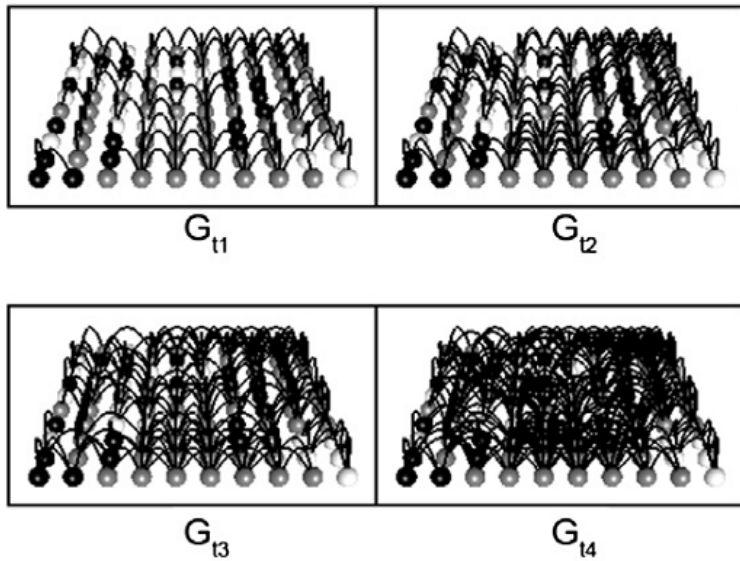
44	31	31	29	35	103	39	29	31
25	23	27	21	42	91	56	20	32
28	18	21	37	69	56	49	21	34
82	20	52	140	70	40	44	30	33
113	17	45	155	52	44	50	35	31
95	20	12	20	58	129	26	32	36
72	28	28	14	60	52	39	34	35
38	15	13	17	53	62	40	27	37
18	16	14	10	38	65	39	26	35

					0,52				
			0,51	0,31	0,26	0,29	0,45		
			0,28	0,28	0,09	0,13	0,29		
			0,57	0,24	0,26	0,07	0,23	0,53	
				0,36	0,17	0,07	0,26	0,33	
				0,49	0,35	0,24	0,28	0,47	
						0,50			



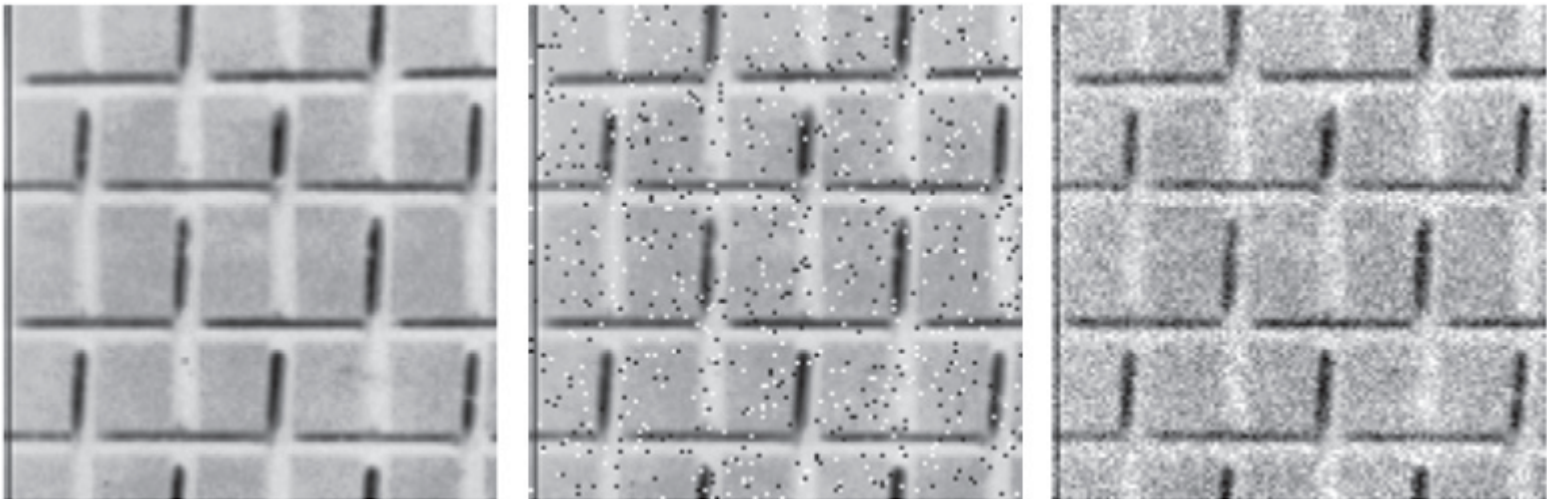
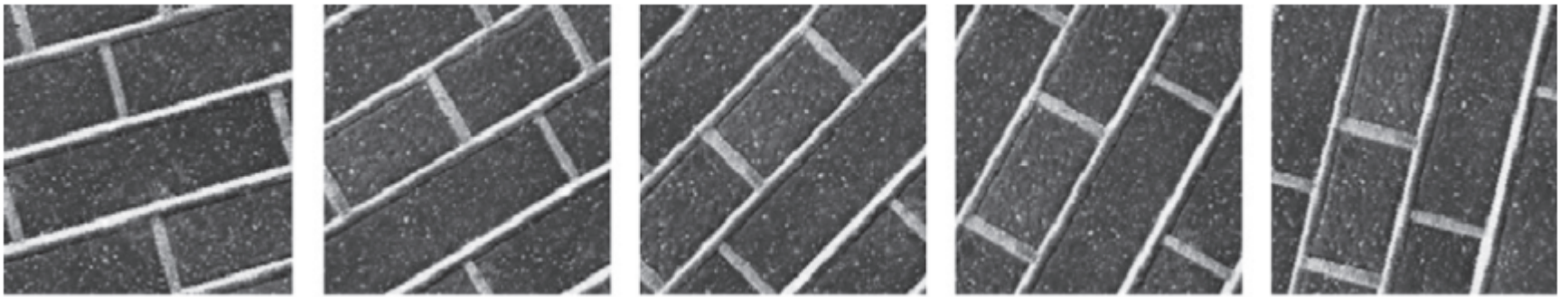
[Chalumeau 2008], [Backes 2010c], [Backes 2013]

Thresholds + features

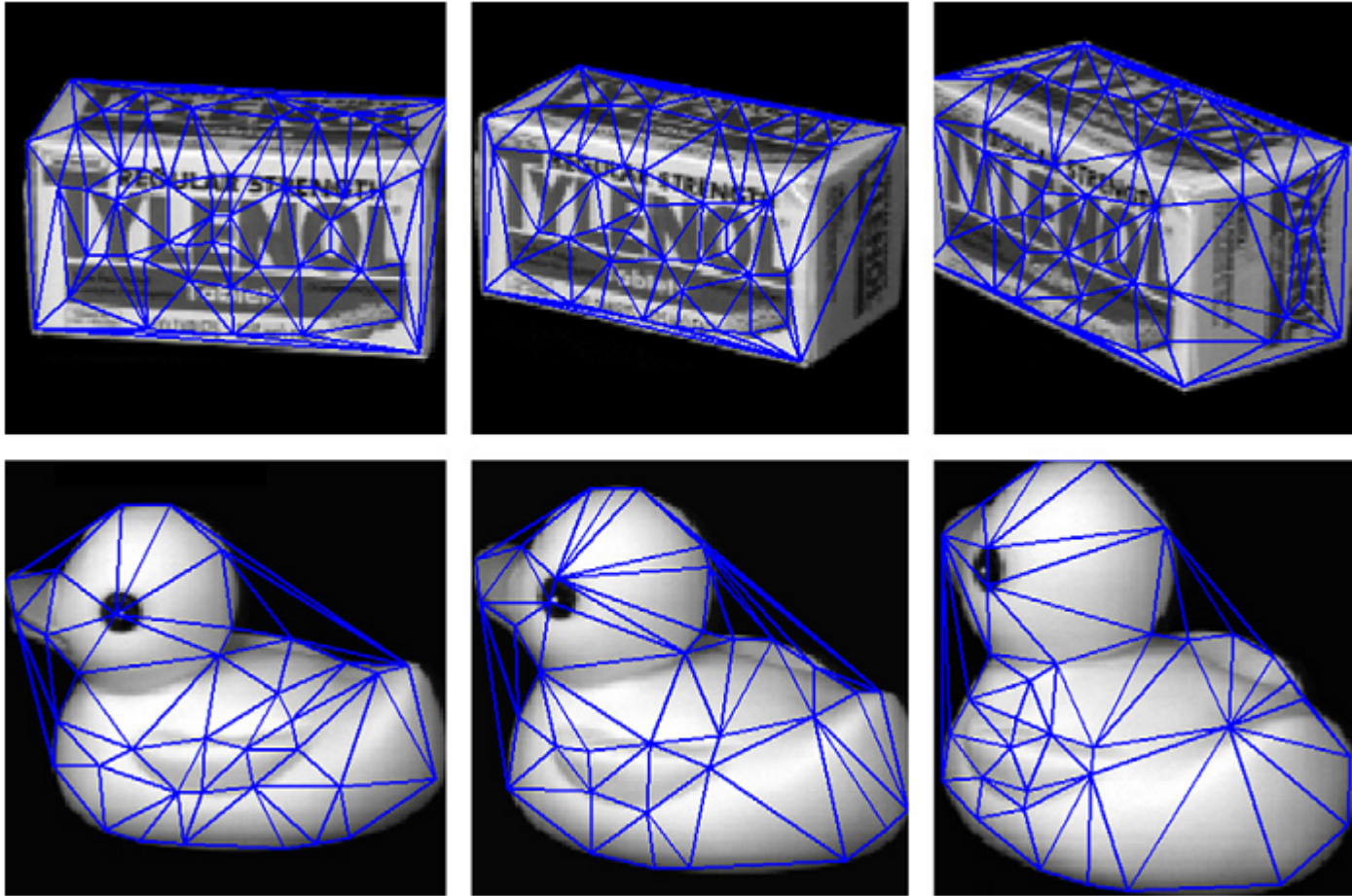


Features: degree, hierarchical degree (avg / min / max)

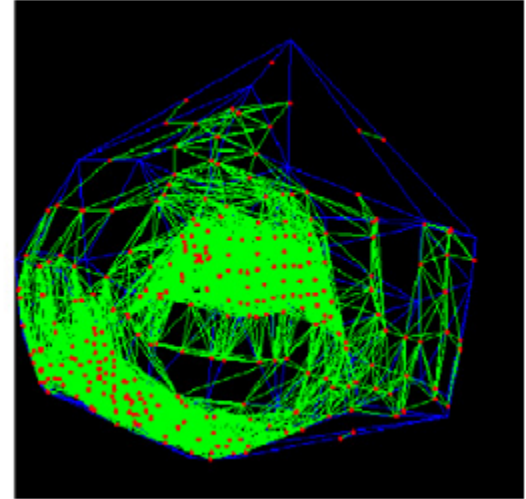
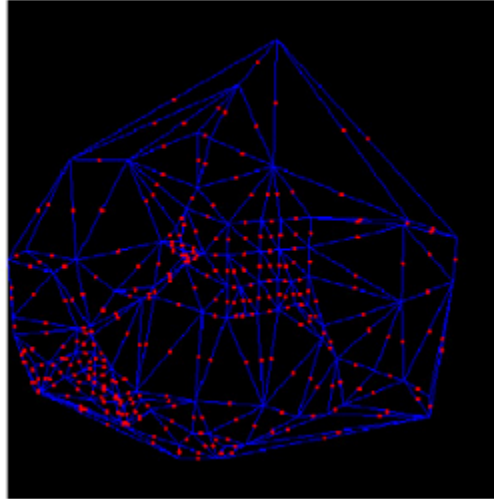
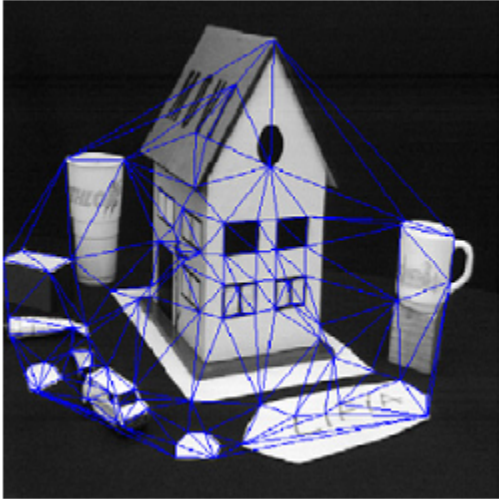
Invariance, robustness



Graph structure analysis



Graph to Network



$$w_{ij} = d(e_i, e_j)$$

$$w_{ij} = W([e_i, e_j])$$

$$W = \frac{W}{\max_{w_{ij} \in W}}$$

$$e_i = (l_i, d_i, d_{1i}, d_{2i}, x_i, y_i),$$

where

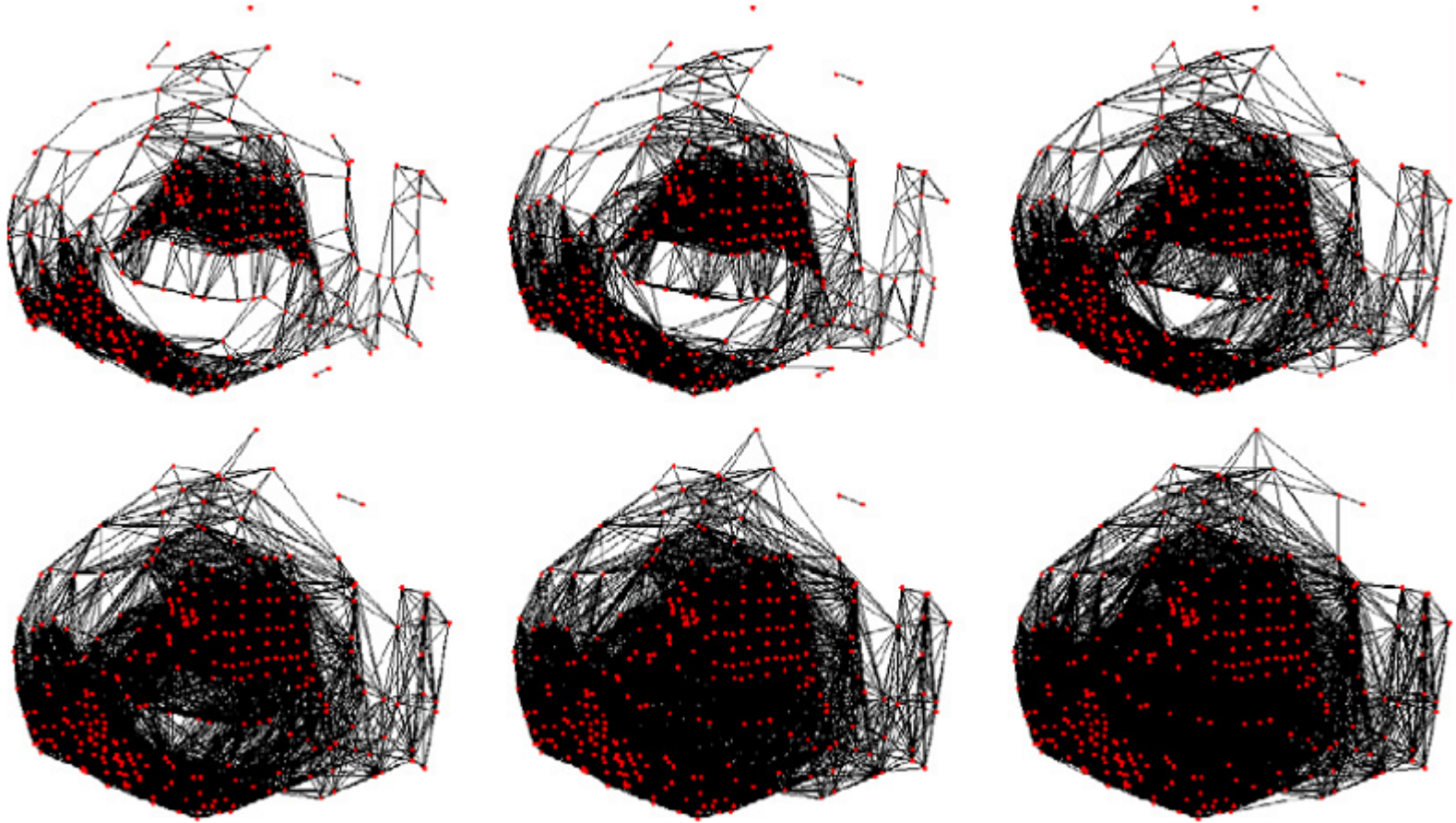
l_i : length of the edge,

d_i : distance between the edge center and the center of the graph, O ,

d_{1i}, d_{2i} : distances from the beginning and end of the edge, respectively, to graph center, O ,

x_i, y_i : coordinates of the center point of the edge.

Thresholds + descriptors

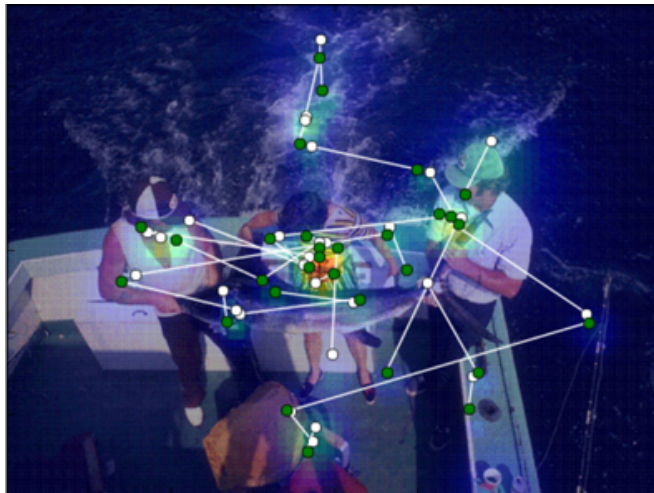
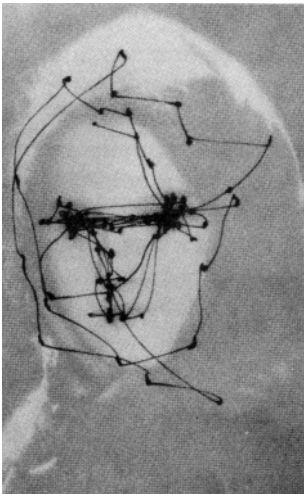


Degree, joint degree, clustering-distance

Saliency

Saccade eye movements + different fixation time = saliency map

=> model them as walks in networks



[Harel 2006], [Costa 2007], [Gopalakrishnan 2010], [Pal 2010], [Kim 2013]

Network construction

Nodes

- pixels
- segments
- blocks

Edges

- local (neighbourhood)
- global (most similar)
- both

Edge weights = (distance in feature space) / (distance in image space)

Features:

- relative intensity
- entropy of local orientations
- compactness of local colour

Random walks

Eigenvector centrality

== stationary distribution for Markov chain

== expected time a walker spends in the node

$$\mathbf{A}(j, i) = w_{ij}$$

$$\mathbf{W}(i, i) = \sum_j w_{ij}$$

$$\mathbf{P} = \mathbf{A}\mathbf{W}^{-1}$$

$$\boldsymbol{\pi} = \mathbf{P}\boldsymbol{\pi}$$

saliency

$$s_i = \frac{\pi(i) - \pi_{\min}}{\pi_{\max} - \pi_{\min}}$$

Random walk with restart (RWR)

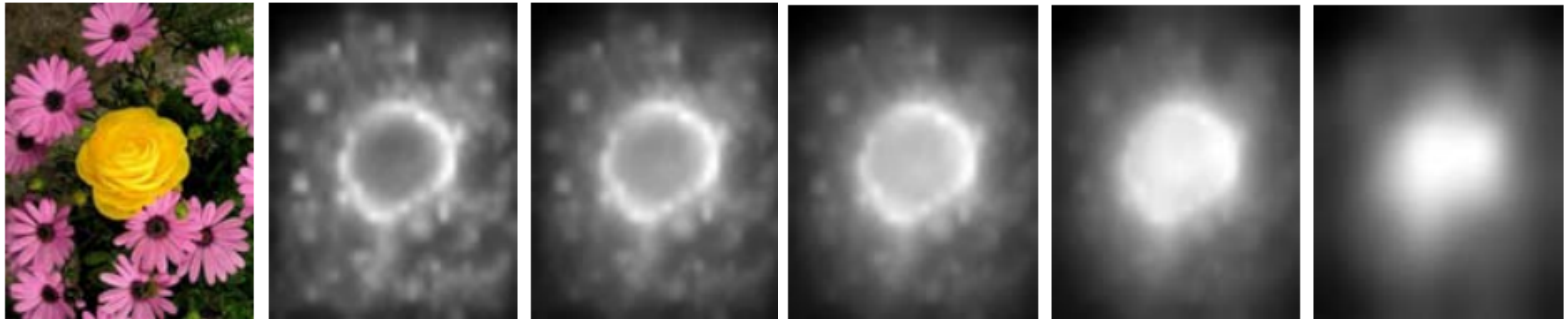
If we have prior info on node importance, we can use RWR.

After finishing a walk, agent restarts it with some probability, choosing new starting node according to an importance map.

The stationary distribution \mathbf{r}_k satisfies

$$\mathbf{r}_k = (1 - \epsilon) \mathbf{P} \mathbf{r}_k + \epsilon \mathbf{e}_k$$

$$\begin{aligned} \mathbf{r}_k &= \epsilon (\mathbf{I} - (1 - \epsilon) \mathbf{P})^{-1} \mathbf{e}_k \\ &= \mathbf{Q} \mathbf{e}_k, \end{aligned}$$

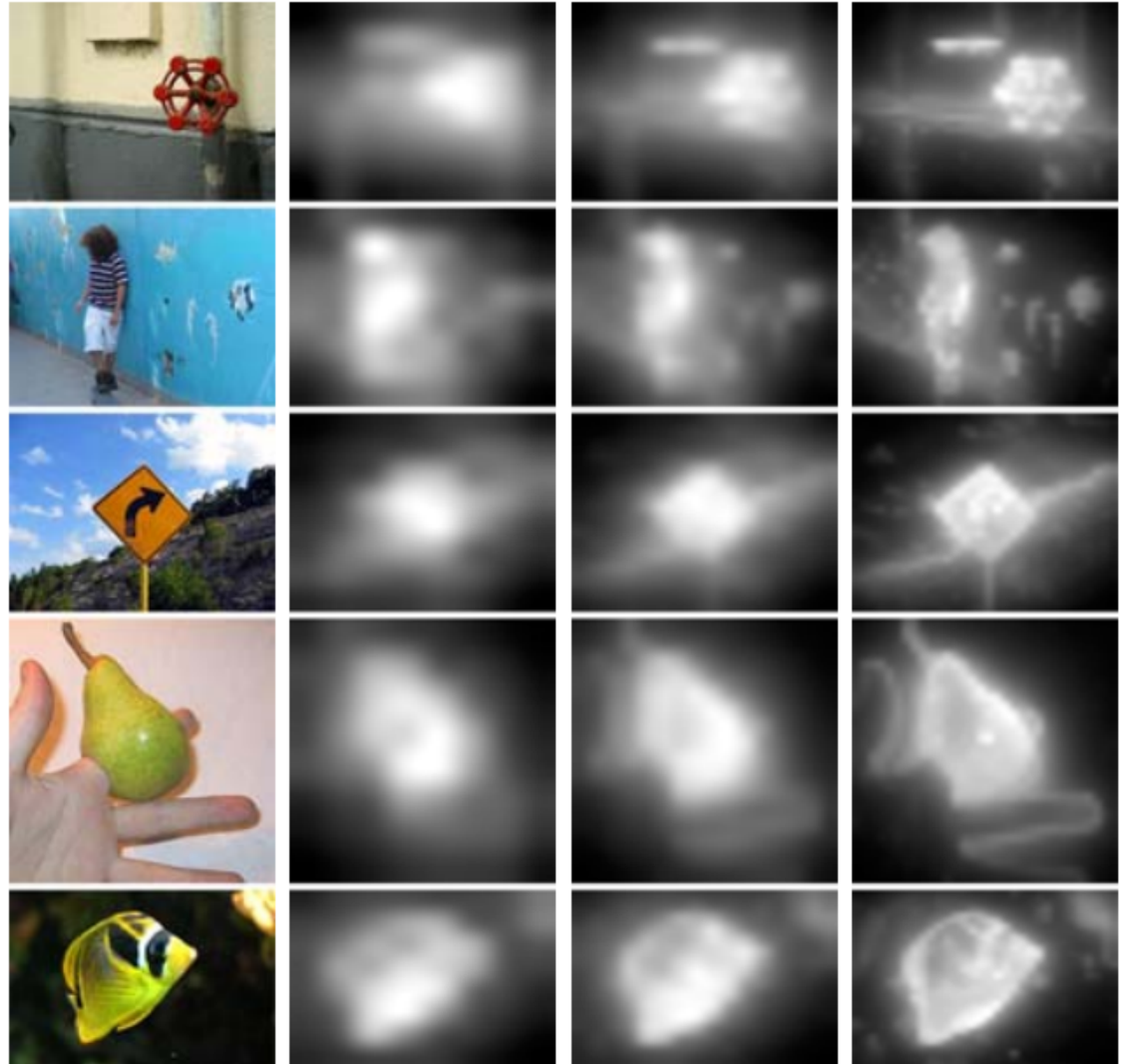


varying restarting probabilities

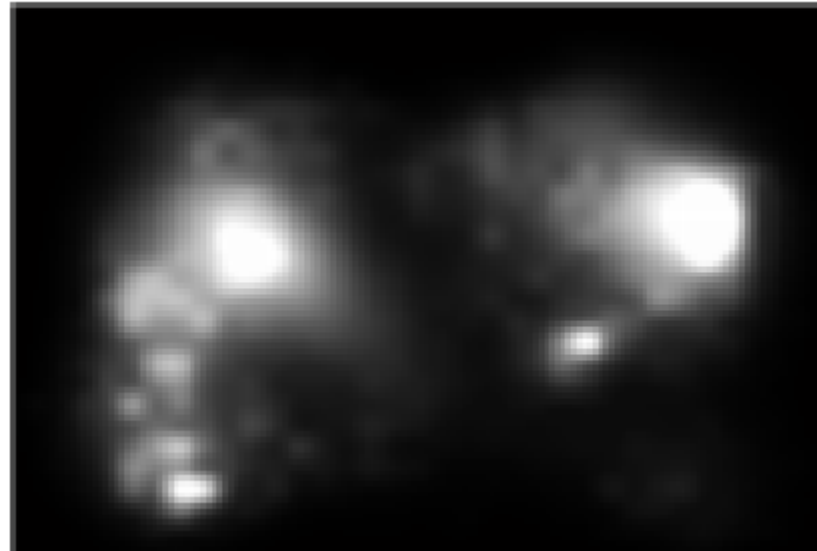
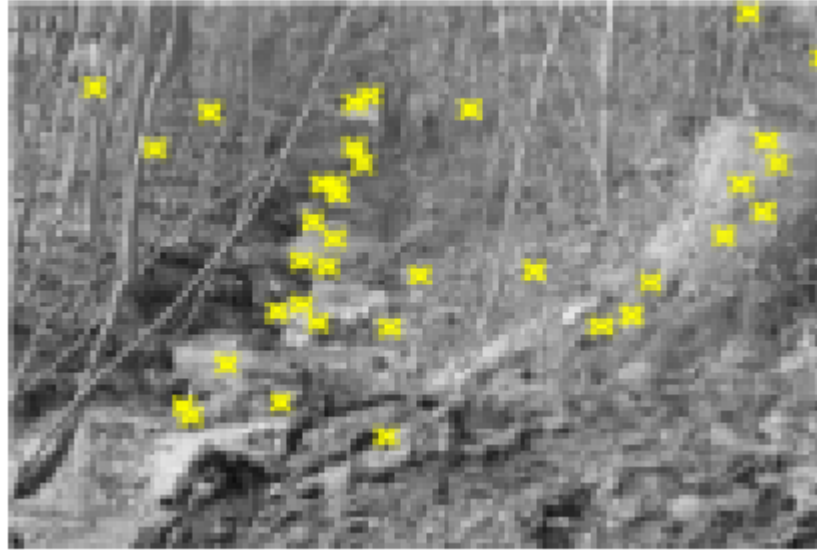
RWR for Multiscale estimation

Using distribution from a coarser scale:

$$\mathbf{r}_\pi^{(l)} = (1 - \epsilon)\mathbf{P}^{(l)}\mathbf{r}_\pi^{(l)} + \epsilon U(\mathbf{r}_\pi^{(l-1)})$$



Compare to real data

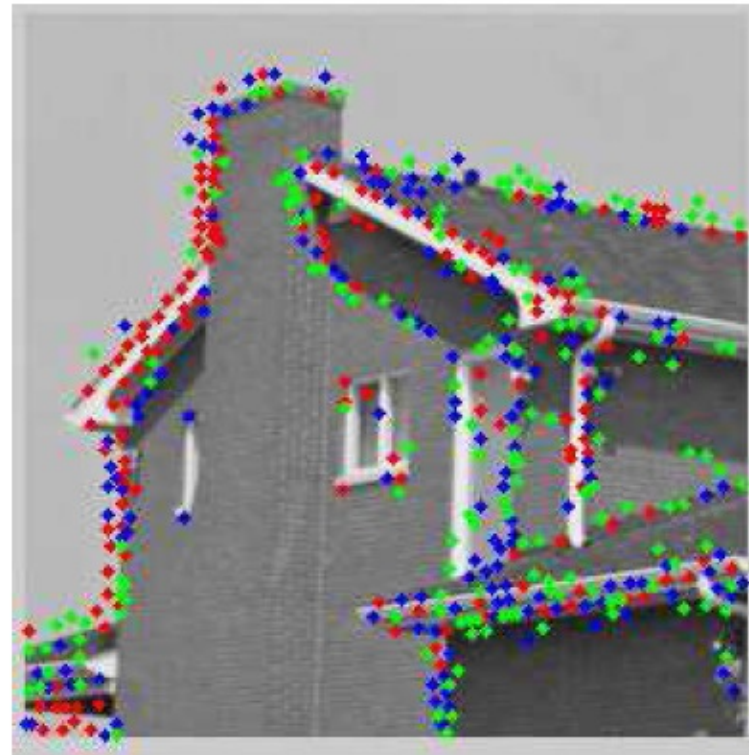


Interest points 1

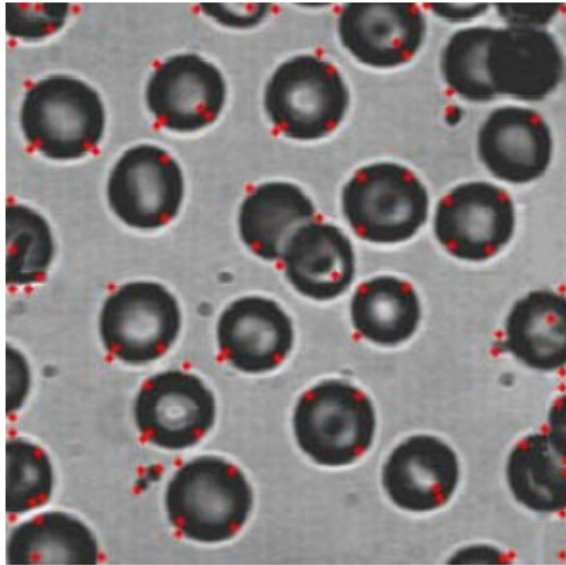
nodes = segments

$$s(i) = \sum_{(i,j) \in E} w(i,j)$$

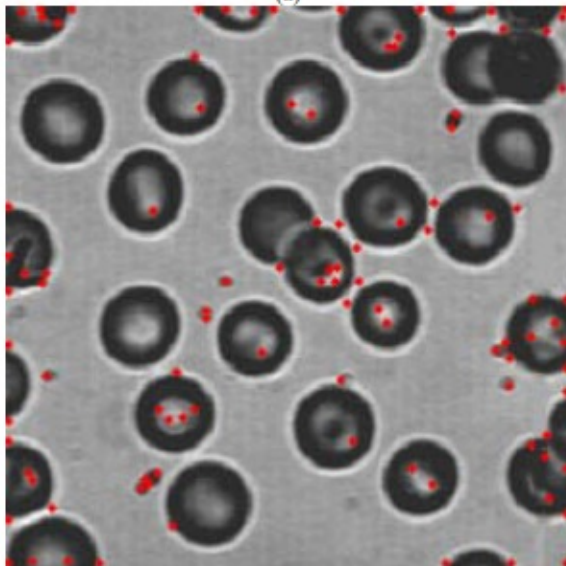
$$w(p_i, p_j) = \begin{cases} |f(p_i) - f(p_j)| & \text{if } r_i \text{ and } r_j \text{ are adjacent} \\ 0 & \text{otherwise.} \end{cases}$$



Interest points 2



(a)



(b)

$I(x), I(y) \in M_{N \times N}$
 gradient of the image † $\omega(I_{ij}, I_{mn}) = |I_{ij} - I_{mn}|$

sliding node window W_{nodes}

$$\omega_{ij} = \sum_{I_{mn} \in W_{nodes}} \omega(x)(I(x)_{ij}, I(x)_{mn}) * \omega(y)(I(y)_{ij}, I(y)_{mn})$$

$$\begin{cases} d_{ij} = \omega_{ij}, & \text{if } d_{ij} > \xi \omega_{\max} \text{ and } d_{ij} > d_{mn} \\ d_{ij} = 0, & \text{otherwise.} \end{cases}$$

Suppress non-interest points for:

$$\begin{cases} |d_{ij} - d_{pq}| < \xi d_{\max} & , i, j, p, q \in (1, N) \\ \sqrt{(p-i)^2 + (q-j)^2} < T \end{cases}$$

Interest points 3

Joint graph:

$G(V, E, W)$

V – vertices: all pix in both images

E – edges: all possible (complete)

W – edge weights: affinity matrix

$W(x,y) = \exp(-\|f(x) - f(y)\|_2 / \sigma \sqrt{2})$

f – descriptor (e.g. SIFT)

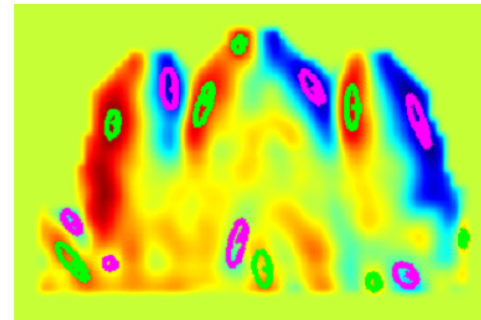
U – first N eigen-vectors of W

J, K – maps of U in image-spaces

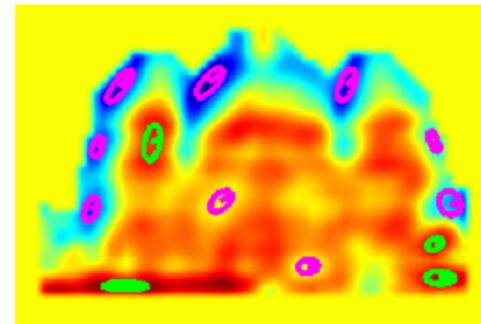
Interest points = stable extrema of J or K

(using MSER blob-detector)

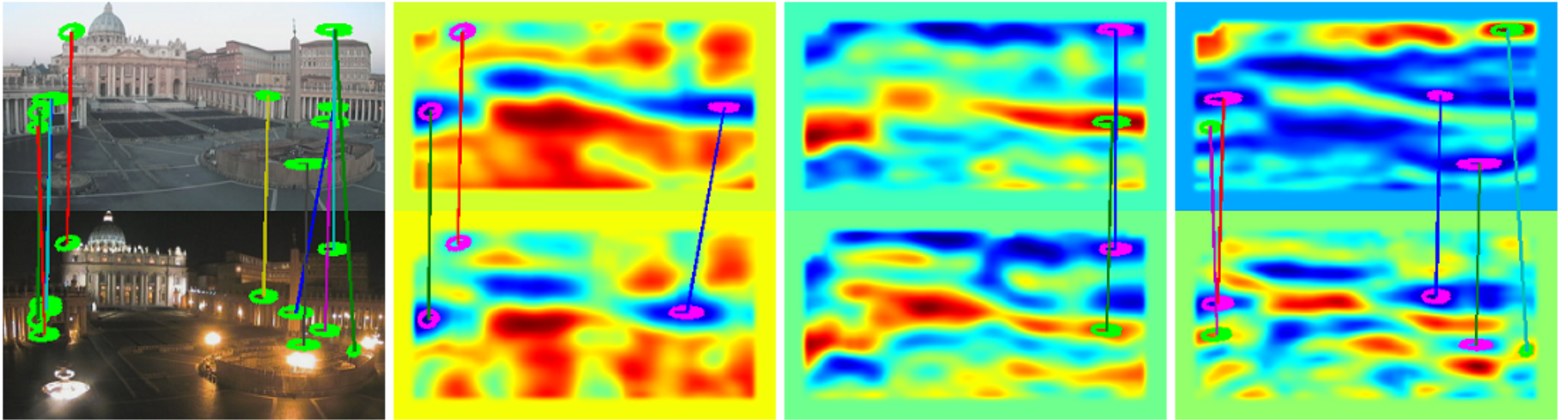
(Maximally Stable Extremal Region)



J



Sample result



Large networks: libraries

- **NetworkX** (python)

<http://networkx.github.io>

- **Boost Graph Library** (C++)

<http://www.boost.org/libs/graph/>

- **MatlabBGL** (sparse matrices + Boost)

<http://dgleich.github.io/matlab-bgl/>

- **PEGASUS** (Hadoop = MapReduce)

<http://www.cs.cmu.edu/~pegasus/>

Large networks: centrality

- **Approximate betweenness** [Brandes 2006]

Estimated from a limited number of single-source shortest-paths computations.

- **K-path centrality** [Kourtellis 2012]

Message traversals from all possible source nodes along random simple paths of at most K edges.

- **HyperLogLog counters** [Boldi 2013]

Geometric centralities on very large graphs estimated in a semi-streaming fashion.

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