Eyelid Position Detection Method for Mobile Iris Recognition

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Introduction



Fig. 1 Image quality degradation: (a) – gaze away, eyelid occlusion, (b) – overexposure, (c, d) – poor contrast, reflection from glass surface

Problem statement

Conventional eyelid detection approach:

- Eyelid noise removal
- Iris image quality estimation



Iris-sclera boundary localization



Eyelid boundary localization

Drawbacks of existing methods:

- Not robust in case of unconstrained conditions
- Most of them are computationally complex
- Performed after complex operations of iris center definition and irissclera boundary localization



Problem statement

Existing methods examples:

Author	Preprocessing	Localization	
Daugman	Gaussian blur	Parabolic IDO	
Wildes	Sobel	Hough transform	
Masek	Sobel	Line fitting (least squares)	
Kang & Park	Sobel (modified)	Parabolic IDO	
Xiangde et al.	1D peak shape filter	Parabolic IDO	
Adam et al.	Anisotropic diffusion	Hough transform	
Yang et al.	Asymmetric Canny	Parabola fitting (least squares)	
Kim, Cha at al.	Histogram equalization	Local minima search	
He et al.	1D rank filter	Pre-established model fitting	

$$max_{a,k,h}\left|\sum_{a}\sum_{k}F*\frac{d}{dh}\sum_{h}(y-k^{2})-4a(x-h)\right|$$





Proposed solution

Idea:

- Detection of eyelid position earlier: for definition of E_u and E_l points (see pic. below) right after pupil-iris boundary localization stage
- Use this information further for:
 - eye opening condition estimation
 - iris-sclera boundary localization algorithm parameters readjustment
 - full eyelid boundary localization/refinement
- If eye isn't opened enough:
 - proceed to the next frame immediately
 - provide user with feedback like: "Open eye fully"







feedback to user



Fig. 5 Proposed flowchart modification 6

 E_u – upper eyelid position point, E_l – lower eyelid position point, P_c – pupil center point

Algorithm Description



Fig. 6 proposed algorithm structure

Algorithm Description







Fig. 8 Choosing between two peaks rule



Fig. 9 Final eyelid position selection from edge map

Experimental Results

Eyelid detection accuracy measurement:

• evaluation method – admissible error rate: $\xi_{1..N_e}^{adm} = \{5\%, 10\%, 15\%\}$



Fig. 10 Different admissible error examples

Fig. 11 Correct and incorrect eyelid position definition examples

• \mathcal{E}_i define a part of the images in single dataset are **not accepted** (found eyelid position isn't in admissible range):

$$\mathcal{E}_j = \frac{1}{N} \left| \left\{ \forall i : |E(x, y_A)_i - E(x, y_M)_i| > \xi_j^{adm} * height \right\} \right|$$

• Then \mathcal{E}_j *averaged* for different datasets:

$$AVG_{\xi_j^{adm}} = \frac{100\%}{N_D} \sum_{i=1}^{N_D} (1.0 - \mathcal{E}_j^i)$$

where $E(x, y_A)_i$ - eyelid point detected by algorithm, $E(x, y_M)_i$ - eyelid point manually marked, N_D - number of datasets used 9

Experimental Results

- Testing data information & results:
 - 4 different datasets are used: MIR-Train, CASIA4-Thousand, CASIA3-Lamp and AOPTIX
 - ≥ 500 images of each dataset have been cropped and manually marked by expert and used for testing



Experimental Results

• Accuracy testing results for $\xi^{adm} = 5\%$

Dataset	MIR	CS4	CS3	APX	AVG
Daugman	76	70	83	84	74,4
Wildes	80	83	92	74	80,6
Masek	50	70	90	93	72,6
Kang & Park	86	89	90	88	86,0
Xiangde et al.	56	92	95	94	83,2
Adam et al.	80	83	91	78	81,2
Yang et al.	55	83	78	90	72,4
Kim, Cha et al.	89	89	99	98	89,0
He et al.	80	83	92	74	80,6
2DGF+IDO	93	90	95	91	92,3
Proposed	98	97	97	91	94,8

Table 1. Upper eyelid detection accuracy (%) for $\xi^{adm} = 5\%$

Dataset	MIR	CS4	CS3	APX	AVG
Daugman	88	86	95	94	90,8
Wildes	87	78	92	92	87,3
Masek	40	65	86	95	71,5
Kang & Park	96	88	95	94	93,3
Xiangde et al.	77	87	87	92	85,8
Adam et al.	87	79	93	95	88,5
Yang et al.	12	28	34	72	36,5
Kim, Cha et al.	30	50	22	32	33,5
He et al.	87	78	92	92	87,3
2DGF+IDO	97	86	92	96	92,8
Proposed	99	94	96	94	95,8

Table 2. Lower eyelid detection accuracy (%) for $\xi^{adm} = 5\%$

Summary

- Proposed method:
 - outperform all the existing methods by accuracy \rightarrow reliable
 - robust on different datasets → applicable for mobile applications, could be used for another purposes: gaze tracking, fatigue detection etc.
 - allows to detect eyelid position on early stages → saves processing time, allows to give user a feedback quickly
 - processing time is about $\leq 1ms$ on Snapdragon 800 (2,26GHz), single core \rightarrow fast & simple

Q&A

Thank you.